

Πανεπιστήμιο Κρήτης
Τμήμα Μαθηματικών και Εφαρμοσμένων Μαθηματικών

Κυματική Διάδοση

4^η διάλεξη
2023-2024

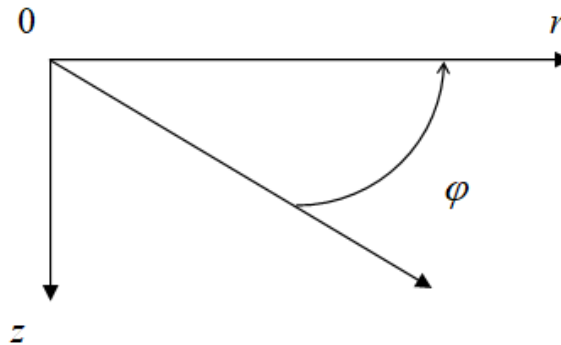
Μιχάλης Ταρουδάκης

Κυλινδρικό Σύστημα

$$\nabla^2 p + \frac{\omega^2}{c^2} p = 0$$

Εξίσωση Helmholtz
(αρμονικά κύματα)

$$\nabla^2 \equiv \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2}{\partial \varphi^2} + \frac{\partial^2}{\partial z^2}$$



$$x = r \cos \varphi, \quad y = r \sin \varphi, \quad z = z$$

Κυλινδρικό Σύστημα

$$\nabla^2 p + \frac{\omega^2}{c^2} p = 0$$

$$\frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial p}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 p}{\partial \varphi^2} + \frac{\partial^2 p}{\partial z^2} + k^2 p = 0$$

$$p(r, z, \varphi) = F(r, \varphi)u(z)$$

Κυλινδρικό Σύστημα

$$p(r, z, \varphi) = F(r, \varphi)u(z)$$

$$\frac{1}{rF} \frac{\partial}{\partial r} \left(r \frac{\partial F}{\partial r} \right) + \frac{1}{r^2 F} \frac{\partial^2 F}{\partial \varphi^2} + \frac{1}{u} \frac{d^2 u}{dz^2} + k^2 = 0$$

$$\frac{1}{u} \frac{d^2 u}{dz^2} + k_z^2 = 0$$

$$\frac{1}{rF} \frac{\partial}{\partial r} \left(r \frac{\partial F}{\partial r} \right) + \frac{1}{r^2 F} \frac{\partial^2 F}{\partial \varphi^2} + q^2 = 0$$

$$k^2 = k_z^2 + q^2$$

Κυλινδρικό Σύστημα

$$\frac{1}{u} \frac{d^2 u}{dz^2} + k_z^2 = 0$$

$$u(z) = D_1 e^{ik_z z} + D_2 e^{-ik_z z}$$

$$F(r, \varphi) = R(r)\Phi(\varphi)$$

$$\frac{1}{R} \left(\frac{d^2 R}{dr^2} + \frac{1}{r} \frac{dR}{dr} \right) + \frac{1}{r^2 \Phi} \frac{d^2 \Phi}{d\varphi^2} = -q^2$$

Κυλινδρικό Σύστημα

$$\frac{1}{rF} \frac{\partial}{\partial r} \left(r \frac{\partial F}{\partial r} \right) + \frac{1}{r^2 F} \frac{\partial^2 F}{\partial \varphi^2} + q^2 = 0$$

$$F(r, \varphi) = R(r)\Phi(\varphi)$$

$$\frac{r^2}{R} \left(\frac{d^2 R}{dr^2} + \frac{1}{r} \frac{dR}{dr} \right) + q^2 r^2 = - \frac{1}{\Phi} \frac{d^2 \Phi}{d\varphi^2}$$

$$\frac{d^2 \Phi}{d\varphi^2} = -m^2 \Phi \quad \frac{1}{R} \left(\frac{d^2 R}{dr^2} + \frac{1}{r} \frac{dR}{dr} \right) + \left(q^2 - \frac{m^2}{r^2} \right) = 0$$

Κυλινδρικό Σύστημα

$$\frac{d^2\Phi}{d\varphi^2} = -m^2\Phi$$

$$\Phi = E_1 e^{im\varphi} + E_2 e^{-im\varphi}$$

$$\frac{1}{R} \left(\frac{d^2 R}{dr^2} + \frac{1}{r} \frac{dR}{dr} \right) + \left(q^2 - \frac{m^2}{r^2} \right) = 0$$

Εξίσωση Bessel

Η Εξίσωση Bessel

$$\frac{1}{R} \left(\frac{d^2 R}{dr^2} + \frac{1}{r} \frac{dR}{dr} \right) + \left(q^2 - \frac{m^2}{r^2} \right) = 0$$

$$\left[x^2 \frac{d^2}{dx^2} + x \frac{d}{dx} + (x^2 - \nu^2) \right] f(x) = 0$$

Εξίσωση Bessel ν τάξης

Λύσεις	$J_\nu(x)$	$N_\nu(x)$	Neumann
	$H_\nu^{(1)}(x)$	$H_\nu^{(2)}(x)$	Hankel

Η εξίσωση Bessel

$$J_\nu(x) = \sum_{n=0}^{\infty} \frac{(-1)^n}{n! \Gamma(\nu + n + 1)} \left(\frac{x}{2}\right)^{2n+\nu}$$

$$J_{-\nu}(x) = \sum_{n=0}^{\infty} \frac{(-1)^n}{n! \Gamma(-\nu + n + 1)} \left(\frac{x}{2}\right)^{2n-\nu}$$

$$J_m(x) = \sum_{n=0}^{\infty} \frac{(-1)^n}{n!(n+m)!} \left(\frac{x}{2}\right)^{2n+m} \quad \text{Για } m \text{ ακέραιο}$$

Συναρτήσεις Neumann

$$N_m(x) = \frac{1}{\pi} \left\{ \frac{\partial J_m}{\partial m} - (-1)^m \left(\frac{\partial J_{-m}}{\partial m} \right) \right\}$$

Η εξίσωση Bessel

Συναρτήσεις Hankel

$$H_\nu^{(1)}(x) = J_\nu(x) + iN_\nu(x)$$

$$H_\nu^{(2)}(x) = J_\nu(x) - iN_\nu(x)$$

$$\text{για } x \rightarrow 0 \left\{ \begin{array}{l} J_\nu(x) \rightarrow \frac{1}{\Gamma(\nu+1)} \left(\frac{x}{2}\right)^\nu \quad \nu \geq 0 \\ N_\nu(x) \rightarrow \left\{ \begin{array}{l} \frac{2}{\pi} [\ln(\frac{x}{2}) + \gamma], \quad \nu = 0 \\ -\frac{\Gamma(\nu)}{\pi} \left(\frac{2}{x}\right)^\nu, \quad \nu > 0 \end{array} \right. \end{array} \right.$$

$$\gamma = -\int_0^\infty e^{-t} \ln t dt$$

Η εξίσωση Bessel

$$\text{για } x \gg \left\{ \begin{array}{l} J_\nu(x) \rightarrow \sqrt{\frac{2}{\pi x}} \cos\left(x - \frac{\nu\pi}{2} - \frac{\pi}{4}\right) \\ N_\nu(x) \rightarrow \sqrt{\frac{2}{\pi x}} \sin\left(x - \frac{\nu\pi}{2} - \frac{\pi}{4}\right) \\ H_\nu^{(1)}(x) \rightarrow \sqrt{\frac{2}{\pi x}} \exp\left\{i\left(x - \frac{\nu\pi}{2} - \frac{\pi}{4}\right)\right\} \\ H_\nu^{(2)}(x) \rightarrow \sqrt{\frac{2}{\pi x}} \exp\left\{-i\left(x - \frac{\nu\pi}{2} - \frac{\pi}{4}\right)\right\} \end{array} \right.$$

Η εξίσωση Bessel

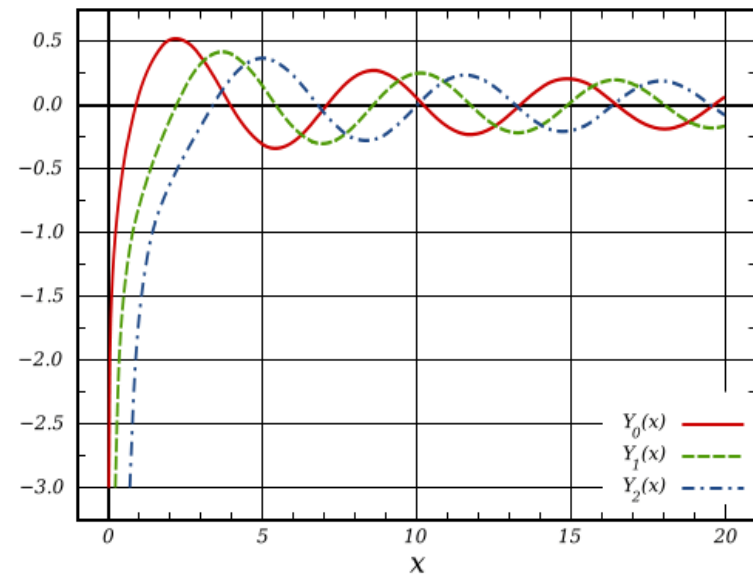
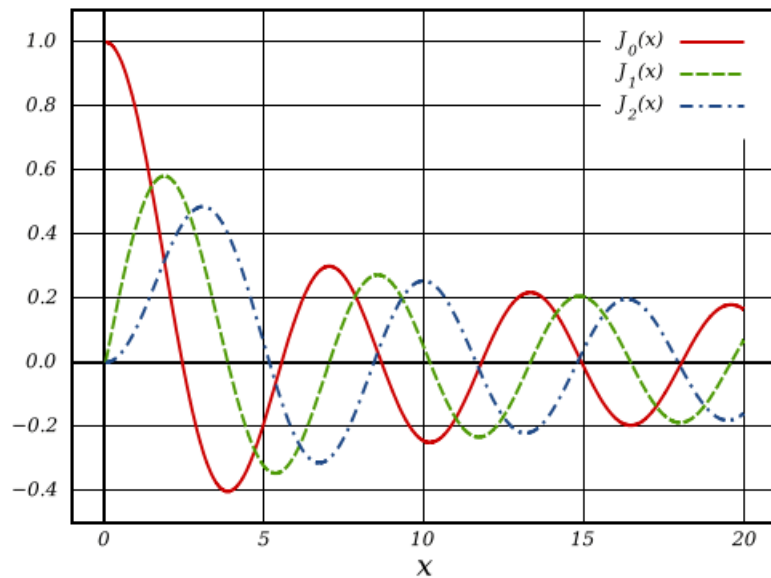
$$f_{\nu-1}(x) + f_{\nu+1}(x) = \frac{2\nu}{x} f_{\nu}(x)$$

$$f_{\nu-1}(x) - f_{\nu+1}(x) = 2 \frac{df_{\nu}(x)}{dx}$$

$$\frac{\nu}{x} f_{\nu}(x) - f_{\nu+1}(x) = \frac{df_{\nu}(x)}{dx}$$

$$f_{\nu-1}(x) - \frac{\nu}{x} f_{\nu}(x) = \frac{df_{\nu}(x)}{dx}$$

Η εξίσωση Bessel



$$N_\nu(x) \rightarrow Y_\nu(x)$$

Η εξίσωση Bessel

$$\frac{1}{R} \left(\frac{d^2 R}{dr^2} + \frac{1}{r} \frac{dR}{dr} \right) + \left(q^2 - \frac{m^2}{r^2} \right) = 0$$

$$\left[x^2 \frac{d^2}{dx^2} + x \frac{d}{dx} + (x^2 - \nu^2) \right] f(x) = 0$$

$$\left[\left(r^2 \frac{d^2}{dr^2} + r \frac{d}{dr} \right) + \left((qr)^2 - m^2 \right) \right] R = 0$$

$$R(r) = E_3 J_m(qr) + E_4 N_m(qr)$$

$$R(r) = E_5 H_m^{(1)}(qr) + E_6 H_m^{(2)}(qr)$$

Η εξίσωση Bessel

$$R(r) = E_5 H_m^{(1)}(qr) + E_6 H_m^{(2)}(qr)$$

$qr \gg$

$$H_m^{(1)}(qr) \rightarrow \sqrt{\frac{2}{\pi qr}} \exp\left\{i\left(qr - \frac{m\pi}{2} - \frac{\pi}{4}\right)\right\}$$

$$H_0^{(1)}(qr) \rightarrow \sqrt{\frac{2}{\pi qr}} \exp\left\{i\left(qr - \frac{\pi}{4}\right)\right\}$$

Κυματική εξίσωση στο κυλινδρικό σύστημα συντεταγμένων

$$\frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial p}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 p}{\partial \varphi^2} + \frac{\partial^2 p}{\partial z^2} + k^2 p = 0$$

$$p(r, z, \varphi) = F(r, \varphi)u(z)$$

$$\frac{1}{u} \frac{d^2 u}{dz^2} + k_z^2 = 0 \quad u(z) = D_1 e^{ik_z z} + D_2 e^{-ik_z z}$$

$$F(r, \varphi) = R(r)\Phi(\varphi)$$

$$\frac{d^2 \Phi}{d\varphi^2} = -m^2 \Phi \quad \Phi(\varphi) = E_1 e^{im\varphi} + E_2 e^{-im\varphi}$$

Κυματική εξίσωση στο κυλινδρικό σύστημα συντεταγμένων

$$\frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial p}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 p}{\partial \varphi^2} + \frac{\partial^2 p}{\partial z^2} + k^2 p = 0$$

$$\frac{1}{R} \left(\frac{d^2 R}{dr^2} + \frac{1}{r} \frac{dR}{dr} \right) + \left(q^2 - \frac{m^2}{r^2} \right) = 0$$

$$R(r) = E_5 H_m^{(1)}(qr) + E_6 H_m^{(2)}(qr)$$

$$p(r, z, \varphi) = R(r) \Phi(\varphi) u(z)$$

$$p(x, y, z) = p_x(x) p_y(y) p_z(z)$$

} Ίδιο πρόβλημα

Κυματική εξίσωση στο κυλινδρικό σύστημα συντεταγμένων

Αξονική συμμετρία

$$\frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial p}{\partial r} \right) + \frac{\partial^2 p}{\partial z^2} + k^2 p = 0$$



$$\frac{\partial^2 p}{\partial r^2} + \frac{1}{r} \frac{\partial p}{\partial r} + \frac{\partial^2 p}{\partial z^2} + k^2 p = 0$$